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# RFID Real-Time Localization for Flexible Production Environments (REFlex)

3 academic partners

3 industrial partners

3 years of research



Ass.Prof. Dr. Holger Arthaber  
holger.arthaber@tuwien.ac.at



- About the project
  - Research question
  - Goals
  - Consortium
  
- UHF RFID Localization
  - Ranging principle
  - Current research results
  
- Conclusion

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- **Flexible manufacturing systems** – Routing flexibility  
*“determining the next step based on available resources”*
  - *Where are the required (hand) tools?*
  - *Which tools and which pre-products are available?*
- **Commissioning / order picking**  
*“bringing the correct thing from A to B”*
  - *Where is the item?*
  - *Was the correct item taken?*
- **Logistics / inventory**  
*“tracking a product from the production process to being sold”*
  - *Which items are in the box? Are all items in the box?*
  - *Where are the items?*

→ **RFID for identification/localization**

## Chosen technology

### **UHF RFID** (Ultra High Frequency Radio Frequency Identification)

- Read ranges up to 10 m
- Billions of tags already in the market
- Low cost, no battery, read/write operation, optional encryption

## Primary research goal

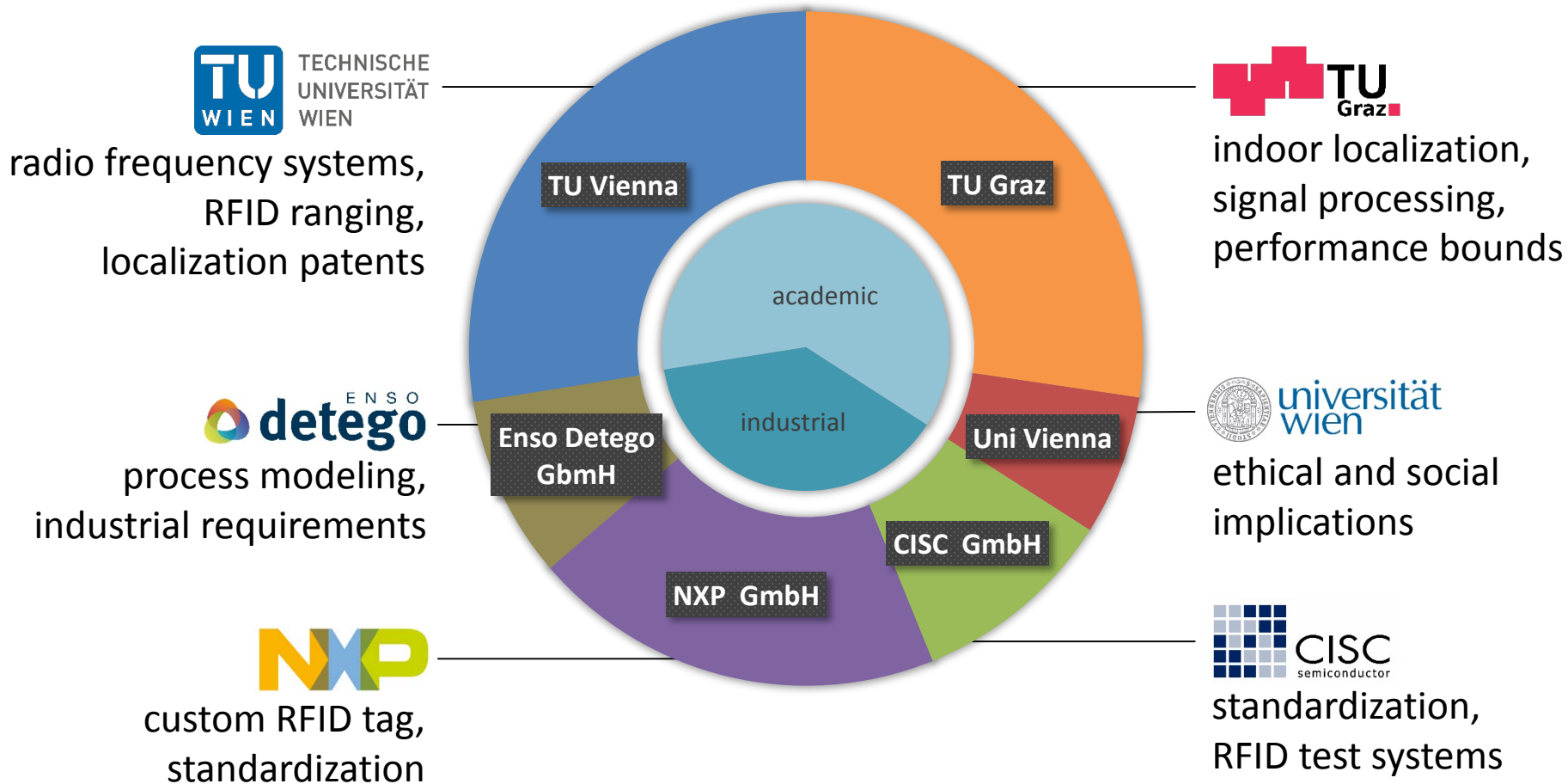
- Use off-the-shelf RFID tags for ranging/localization in flexible production environments

## Sub goals

- Impact onto production processes?
- Ethical and social implications?
- Standardization possible?



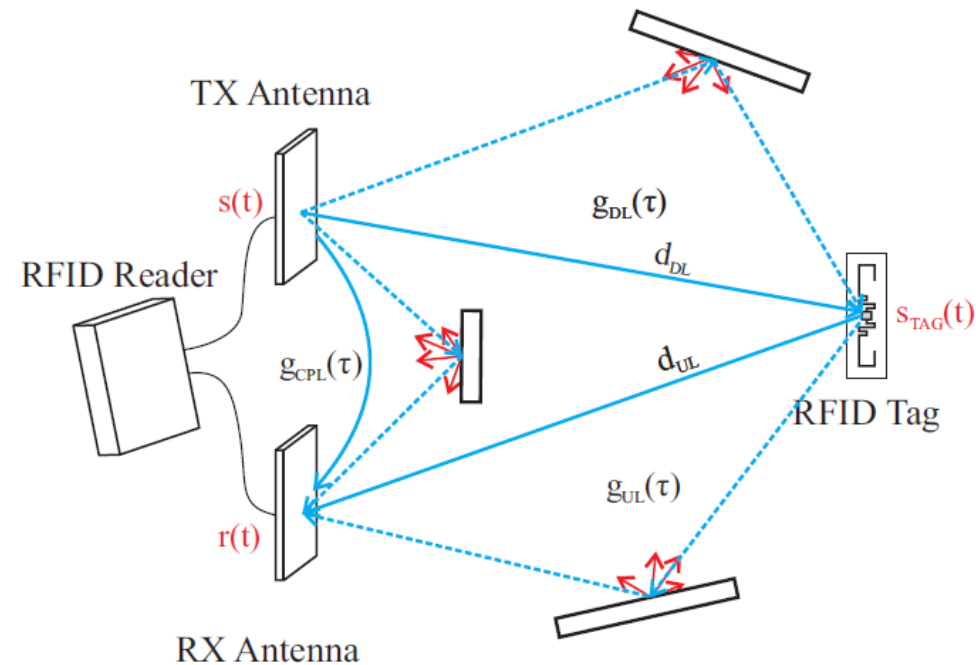
## Project Consortium



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## Localization in backscattering systems

- Available localization algorithms are inaccurate
- No precise timing on tag
- Narrowband system
- High self interference



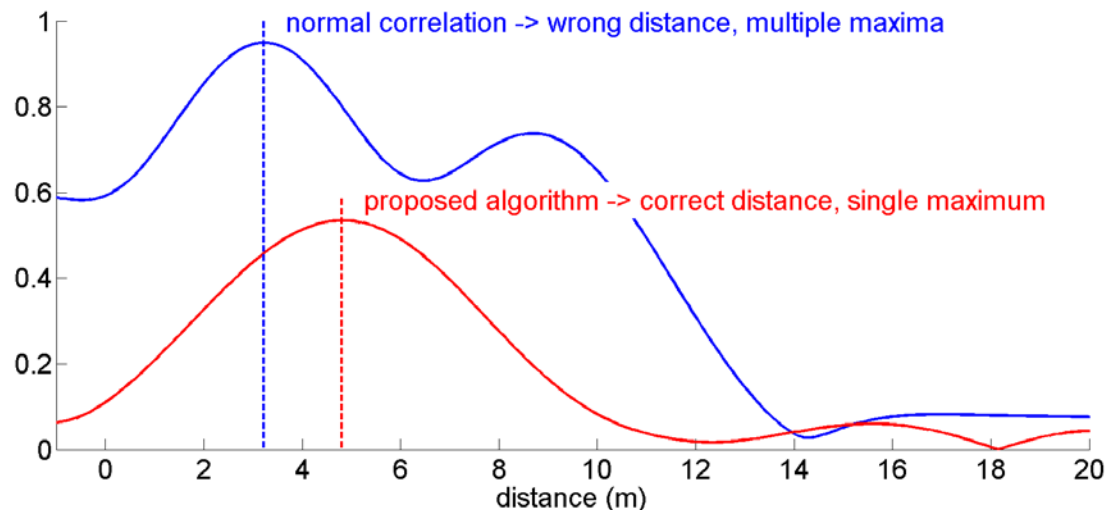
## New approach

- Time of Flight (ToF) method
- Seems impossible at a first glance:
  - High bandwidth needed  $\rightarrow$  use of superimposed spread spectrum ranging signal
  - RFID frequency band is narrow  $\rightarrow$  use extremely low power of ranging signal
  - Static echoes must be suppressed  $\rightarrow$  novel algorithm developed and patented



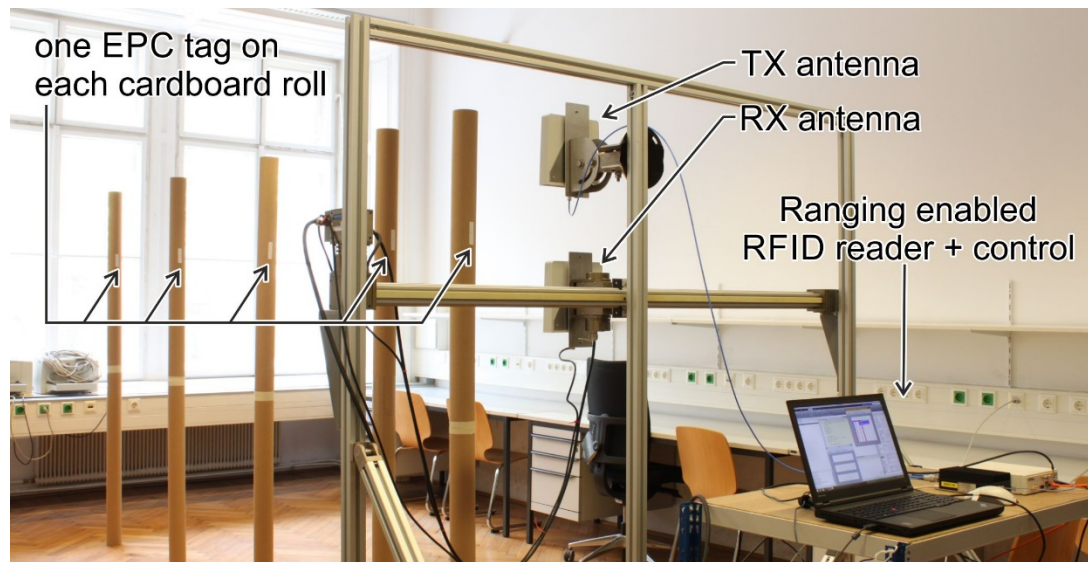
## Developed algorithm

- Direct sequence spread spectrum (DSSS) signal with 25 MChips/s
- DSSS signal is undetected by the tag, does not influence communication
- RFID tag backscatters the DSSS signal as well
- Coherent adding procedure [1] suppresses static echoes and emphasizes the echo from the tag



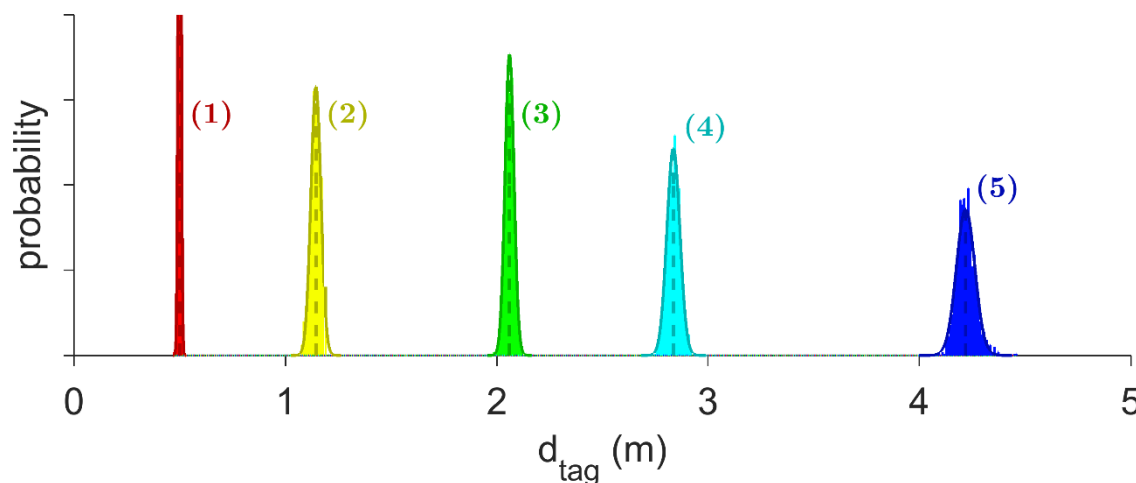
[1] H. Arthaber, T. Faseth, F. Galler, “Spread-Spectrum Based Ranging of Passive UHF EPC RFID Tags”, IEEE Communications Letters, Vol. 19, No. 10, October 2015, ISSN 1089-7798, pp. 1734–1737

## Ranging tests with demonstrator and NXP RFID tags



Tags in distances  
0.5m, 1.0m, 2.0m, 3.0m, 4.0m

1000x ranging for each tag:  
 - max. estimator bias: 22cm  
 - max. standard dev.: 4.4cm



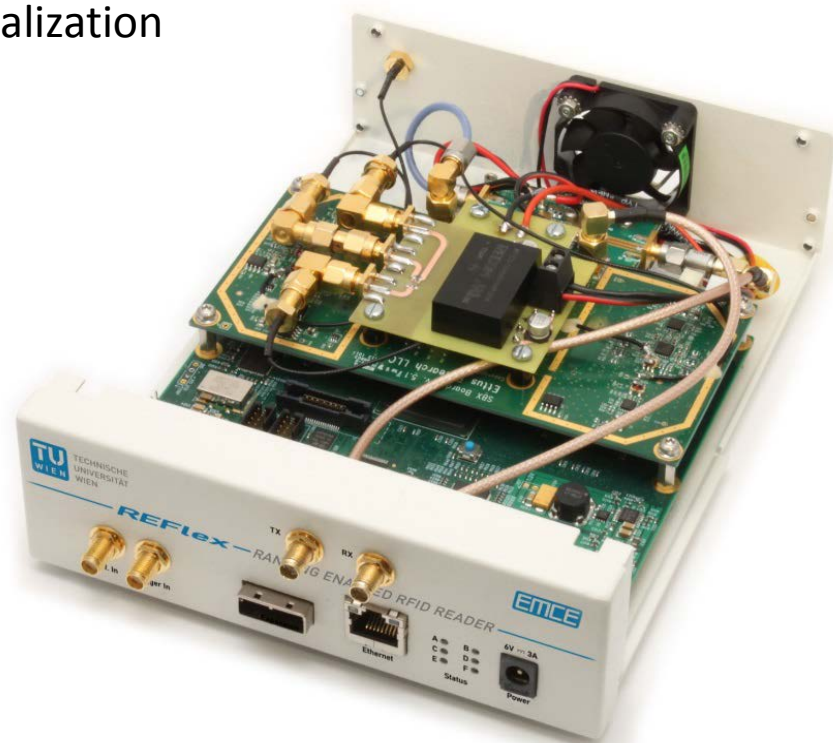
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## REFlex – RFID Real-Time Localization for Flexible Production Environments

- FFG-Program “IKT der Zukunft, 2<sup>nd</sup> call”
- 3 universities, 3 industrial partners, 3 years
- Interdisciplinary research on
  - Production process modeling with RFID localization/ranging
  - Development of a new UHF RFID ranging concept
  - Activities in standardization groups and discussion with regulatory bodies
  - Ethical and social implications of RFID localization

### Subtask “UHF RFID Localization”

- Novel ranging concept developed
- Compatible with off-the-shelf tags
- Demonstrator shows excellent results
- Performance bounds analyzed





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**Thank You For Your Attention!**

Contact:

Ass.Prof. Dr. Holger Arthaber  
holger.arthaber@tuwien.ac.at

Vienna University of Technology  
Institute of Electrodynamics, Microwave and Circuit Engineering  
Microwave Engineering Group  
Gußhausstraße 25/354  
1040 Vienna, Austria



FFG